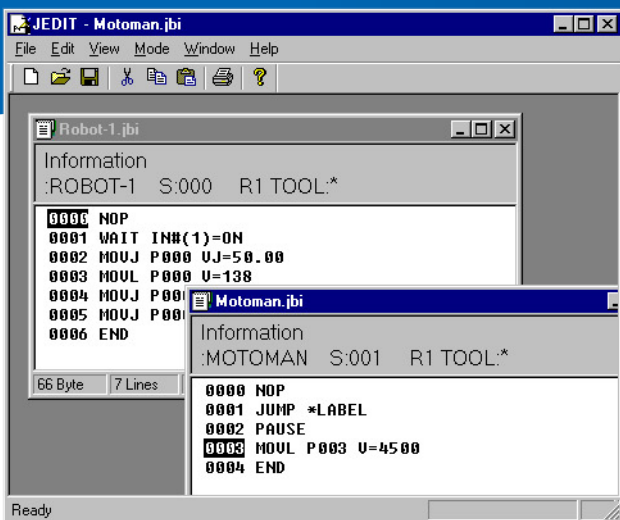# YASKAWA

JobEditor

Creating and editing robot jobs offline.

Key features

- Creating and editing robot jobs offline.
- Create header and comments.
- Create and edit robot commands and conditions.

Key benefits

- Prepare and design robot jobs offline.
- Easy and intuitive interface.
- Directly integrate with robot controller to transfer robot jobs to and from the robot.

Offline programming tool

The JobEditor software makes it possible to create and edit robot jobs offline on a personal computer. The language used is INFORM, and robot jobs are created with the same method as with the programming pendant. This means that anyone that are familiar with programming and editing on the programming pendant ca easily use this software.

When the actual configuration for each robot is imported to the JobEditor it is also possible to create robot programs with a syntax control that makes them free from errors. The type of communication protocols between computer and controller depends on the robot control system. JobEditor is available in a specific version suitable for each controller generation from MRC to YRC1000.

Available for robot controllers

- MRC, XRC, NX100, DX100, DX200, YRC1000 and YRC1000micro.

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